

DEPARTMENT OF CIVIL ENGINEERING

REPORT ON WEBINAR “ AVIATION AND ROBOTICS IN CIVIL ENGINEERING”

The Department of Civil Engineering of KPR Institute of Engineering and Technology conducted an Interactive session on “Aviation and Robotics in Civil Engineering” on 21.09.2021. The main aim of the webinar is to interact and create curiosity among students regarding robotics and its application in civil Engineering.

Dr. S. Arivazhagan, Innovation officer, Aviation and Robotics club, KPRIET. He gave a brief presentation on drone surveying and robotics which are used in the wide range of applications such as Irrigation Engineering, Mine surveying and Ground water monitoring etc.,

Finally, Dr. S. Arivazhagan, Interacted with the participants and answered their questions, Totally 122 participants participated in the webinar.

“Aviation and Robotics in Civil Engineering” on 21.09.2021, 12.00 pm at Raagam Hall.



The poster features a blue header with the KPR Institute of Engineering and Technology logo and name on the left, and the Department of Civil Engineering logo and name on the right. The main title "Aviation and Robotics in Civil Engineering" is centered in large blue font. Below the title, a circular portrait of Dr. S. Arivazhagan is shown. To the right of the portrait, his name and title are listed. A green box contains the event details: DATE: 21.09.2021, TIMING: 12.00 noon, and VENUE: RAAGAM HALL. At the bottom, the Convener (Dr. C. Anusha) and Coordinators (Dr. S. Karmani and Ms. K. Dhivya) are listed. The Sustainable Development Goals logo is in the bottom right corner.

KPR Institute of Engineering and Technology
(Autonomous, NAAC 'A')
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Department of Civil Engineering

Aviation and Robotics in Civil Engineering

RESOURCE PERSON
Dr. S. ARIVAZHAGAN
Innovation Officer
AVIATION AND ROBOTICS CLUB, KPRIET

DATE : 21.09.2021
TIMING : 12.00 noon
VENUE : RAAGAM HALL

Convener:
Dr. C. Anusha
Head/ Civil Department

Coordinators:
Dr. S. Karmani
Ms. K. Dhivya

SUSTAINABLE DEVELOPMENT GOALS



Coordinator

Head/Civil